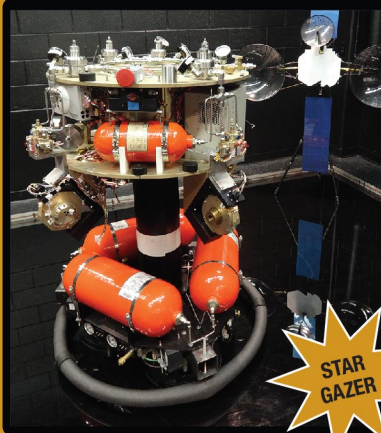


# ASTROS

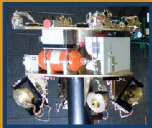


STAR  
GAZER

Autonomous Tester &  
Spacecraft Simulator

Georgia  
Tech 

# ASTROS



**Position:** Autonomous Tester & Spacecraft Simulator

**Coach:** Panagiotis Tsiotras

**Stats:** Boasts 5-dofs for testing rendezvous and docking scenarios between two spacecrafts in orbit; uses 12 thrusters, 4 variable-speed CMGs, rate gyros, cameras, and two on-board computers to navigate autonomously on a frictionless floor

**Hometown:** Dynamics and Control Systems Laboratory

**Fun Fact:** Likes to fight gravity and stare at other people's satellites, but stay away when it fires its thrusters!

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



# ROBOT DRUMMER

BEST  
MUSICIAN



**Robotic Drumming  
Prosthesis**

**Georgia  
Tech** 

# ROBOT DRUMMER



**Position:** Robotic Drumming Prosthesis

**Coach:** Gil Weinberg

**Stats:** Uses novel anticipation algorithms to foresee human actions; triggers responses with low-latency to achieve sub-second human-robot synchronization for drumming; essentially transforms drummer into a cyborg

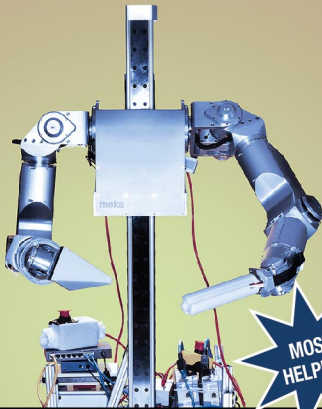
**Hometown:** Center for Music Technology

**Fun Fact:** Debuted publicly on March 22 at the Robotic Musicianship Demonstration and Concert at Kennesaw State University as part of the 2014 Atlanta Science Festival

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



**CODY**



**Helpful Personal  
Assistant**

**Georgia  
Tech** 

# CODY



**Position:** Helpful Personal Assistant

**Coach:** Charlie Kemp

**Stats:** New control method works in tandem with compliant robotic joints and whole-arm tactile sensing to intelligently maneuver within clutter; gently makes contact with objects; includes removable tactile sensors made out of stretchable fabric that fully cover arms

**Hometown:** Healthcare Robotics Lab

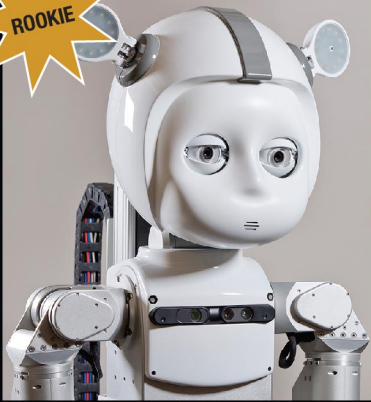
**Fun Fact:** Destined to be an in-home personal assistant, Cody can reach through cinder blocks and dense foliage with its eyes closed!

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



# CURI

ROOKIE



**Personal Service  
Robot & Companion**

**Georgia  
Tech** 

# CURI



**Position:** Personal Service Robot & Companion

**Coach:** Andrea Thomaz

**Stats:** Finds her way with an omnidirectional base and two laser sensors; has series elastic, actuated, 7-degrees of freedom arms that are safe for interaction; an expressive head with a stereo camera pair; and interacts and cooperates with humans to learn new skills

**Hometown:** Socially Intelligent Machines Lab

**Fun Fact:** Captured on video, Curi chose her own name based on submissions from a Twitter contest

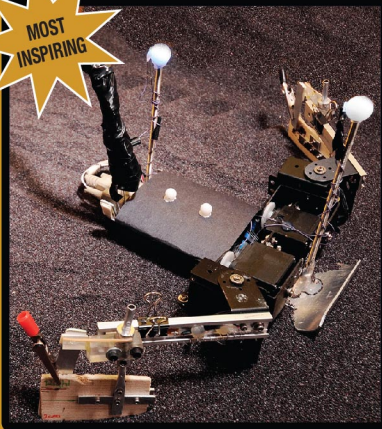
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# FLIPPERBOT

**MOST  
INSPIRING**



**Bio-Inspired  
Terrestrial Navigator**

**Georgia  
Tech** 

# FLIPPERBOT



**Position:** Bio-Inspired  
Terrestrial Navigator

**Coach:** Daniel Goldman

**Stats:** Measures about 19 centimeters in length, weighs about 970 grams, and has two flippers driven by servo motors; like the turtles, has flexible wrists, allowing for variations in movement

**Hometown:** Complex Rheology And Biomechanics Lab (CRAB Lab)

**Fun Fact:** Design inspired by observing hatchling loggerhead sea turtles to discover principles governing their locomotion on sand

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



# PIPER CUB



**Autonomous Unmanned  
Aerial Vehicle (UAV)**

**Georgia  
Tech** 

# PIPER CUB



**Position:** Autonomous UAV

**Coaches:** Georgia Tech  
Research Institute (GTRI)  
Robotics Group Members

**Stats:** Carries a mission computer, radio modem, sensors, and autopilot for autonomous flight; multiple UAVs can fly in autonomous formation; operators transmit new locations to visit and UAVs negotiate with their teammates to identify the best one to perform the task

**Hometown:** GTRI

**Fun Fact:** In June 2013, three Piper Cubs flew together at the same altitude in leader-follower formation over Fort Benning, Ga.

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



# GOOGLE GLASS

**MOST  
POPULAR**



**Wearable Technology  
with OHMD**

**Georgia  
Tech** 

# GOOGLE GLASS



**Position:** Wearable Technology with Optical Head-Mounted Display (OHMD)

**Coach:** Thad Starner

**Stats:** Features tiny computer on earpiece; users can access the Internet and capture photos and videos; combines ambient intelligence with augmented reality for a new kind of human-machine interaction; has potential healthcare applications as assistive devices

**Hometown:** Google, with frequent visits to the Contextual Computing Group

**Fun Fact:** A pioneer of wearable computing, Starner is a technical lead for Glass; he's worn a computer on his head for 20 years!

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)



# GTMAX



**AUTO  
PILOT**

**Autonomous Aerial  
Vehicle System**

**Georgia  
Tech** 

# GTMAX



**Position:** Autonomous Aerial Vehicle System

**Coach:** Eric N. Johnson

**Stats:** Research unmanned aerial vehicle (UAV) based on Yamaha RMAX helicopter; adaptive control system allows it to “learn” to fly better on its own; auto-land and auto-takeoff capabilities; 3-time AUUSI Aerial Robotics Competition winner

**Hometown:** UAV Research Facility (UAVRF)

**Fun Fact:** Performed the first air launch of a hovering sub-vehicle and the first purely vision-based formation flight; has logged more than 1,000 research test flights since 2001

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)





# DECEPTIONBOT

**MOST  
CRAFTY**



**Deception Expert &  
Future Protector**

**Georgia  
Tech** 

# DECEPTIONBOT



**Position:** Deception Expert  
& Future Protector

**Coaches:** Ron Arkin &  
Alan Wagner

**Stats:** Uses algorithms based on interdependence theory framework and game theoretic notation; recognizes situations that warrant deceptive maneuvers and selects the best deceptive strategy to use

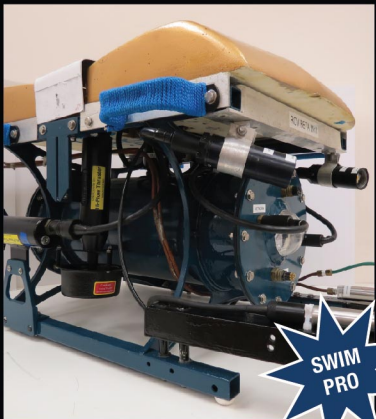
**Hometown:** Mobile Robot Lab

**Fun Fact:** Destined to provide assistance on the battlefield or in civilian rescue operations, DeceptionBot has been keeping busy playing a mean game of hide-and-seek in the lab

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)

**Georgia  
Tech** 

# ROV BETA MK III

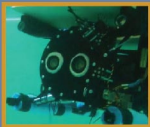


SWIM  
PRO

**Underwater  
Manipulator**

**Georgia  
Tech** 

# ROV BETA MK III



**Position:** Underwater Manipulator

**Coach:** Fumin Zhang

**Stats:** Steel-hulled remote controlled submarine with 100m tether; capable of underwater manipulation tasks such as sampling, opening and closing hatches, and removing damaged riser pipes

**Hometown:** Lab for Autonomous Mobile Networks (LAMON)

**Fun Fact:** Visited Hawaii to survey underwater volcanoes and swim with the dolphins

To learn more:  
[robotics.gatech.edu](http://robotics.gatech.edu)

